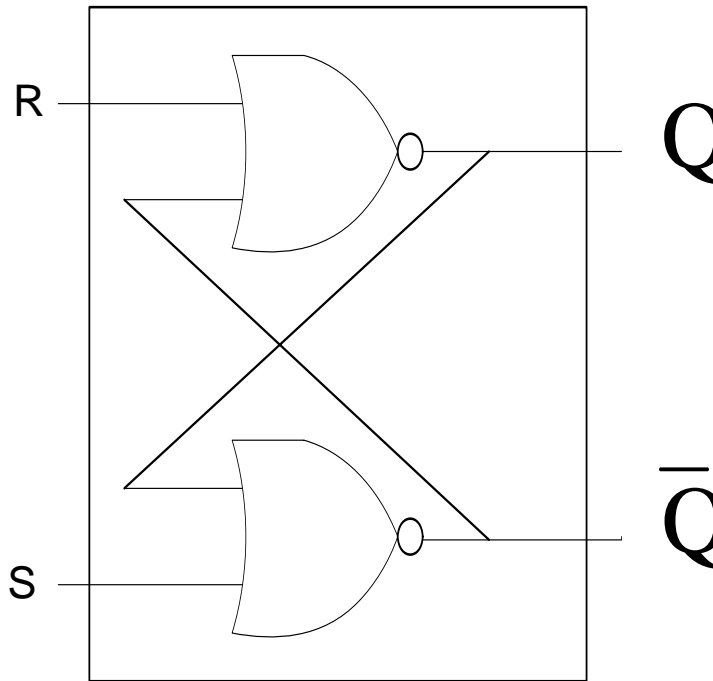


RS Latch

$$Q_+ = S + R' Q$$

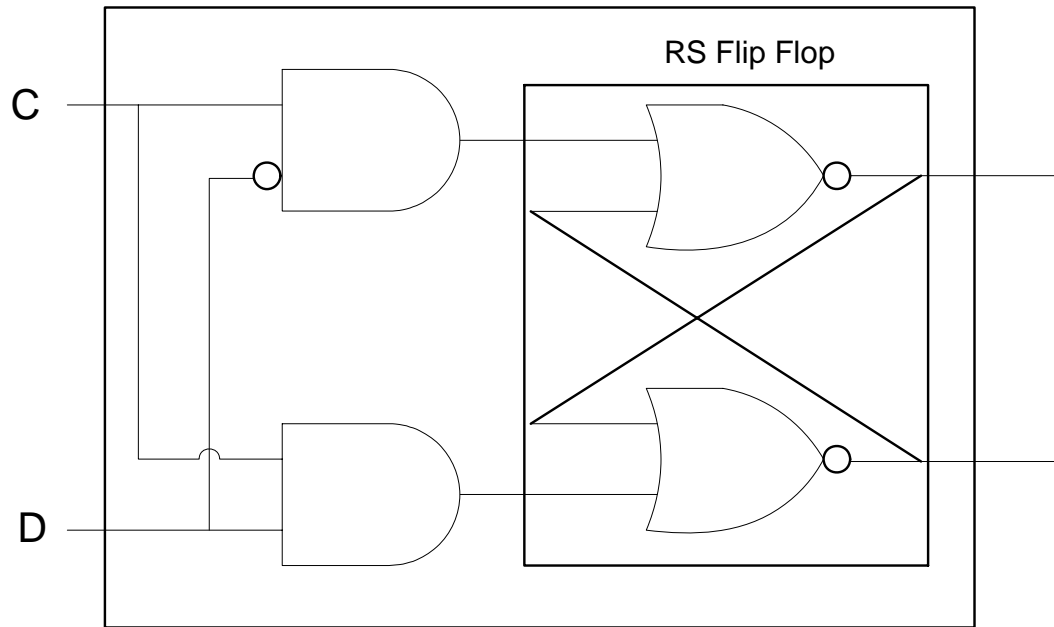


R	S	Q_{t+1}
0	0	\bar{q}_t
0	1	1
1	0	0
1	1	—

Two Problems:

R=S= 1 Not allowed, Data is transparent

The D Latch

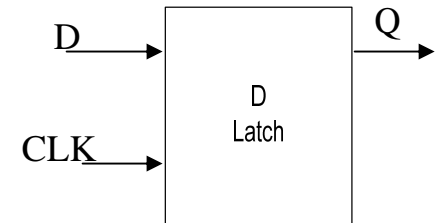
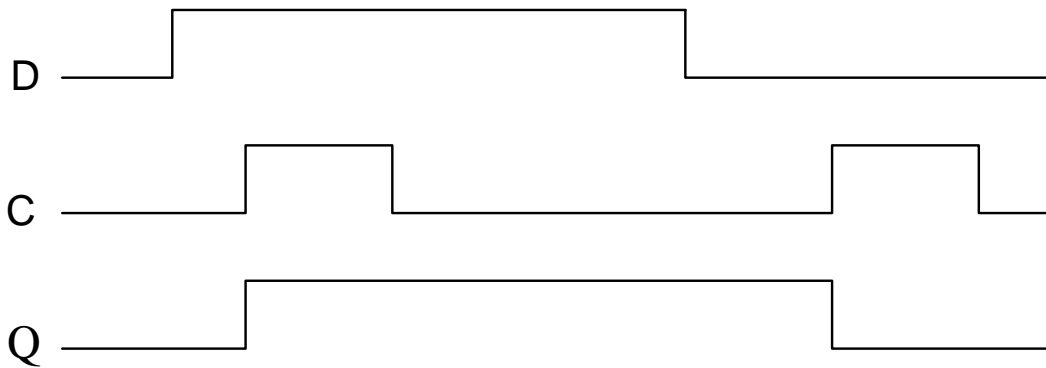


Q

\bar{Q}

D	Q ⁺
0	0
1	1

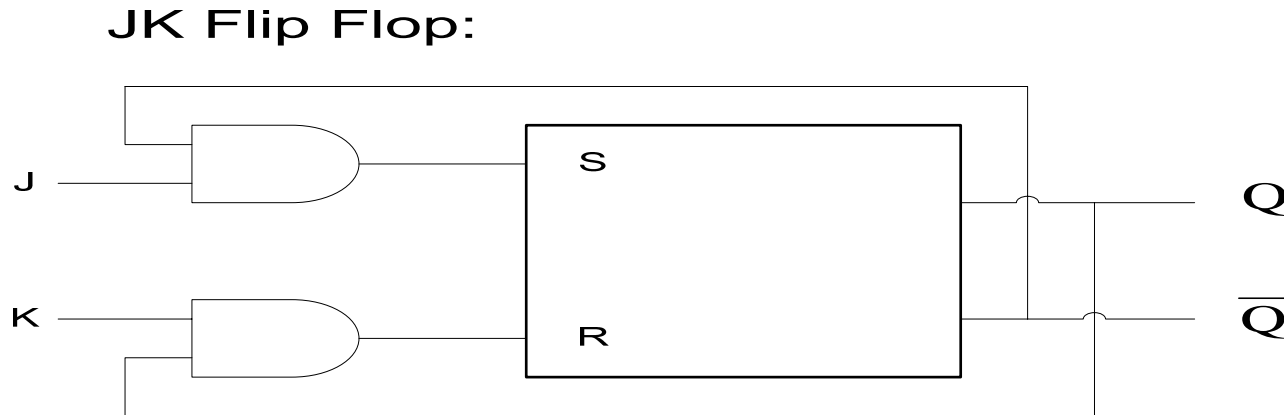
$$Q^+ = D$$



Problem: Level sensitive

JK Latch : Universal, Level sensitive,

Timing Constraints due to feed back.



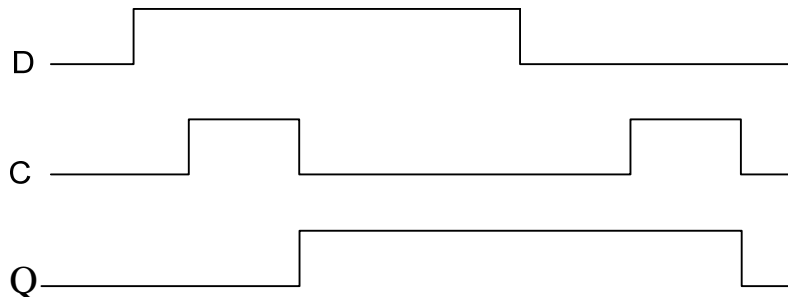
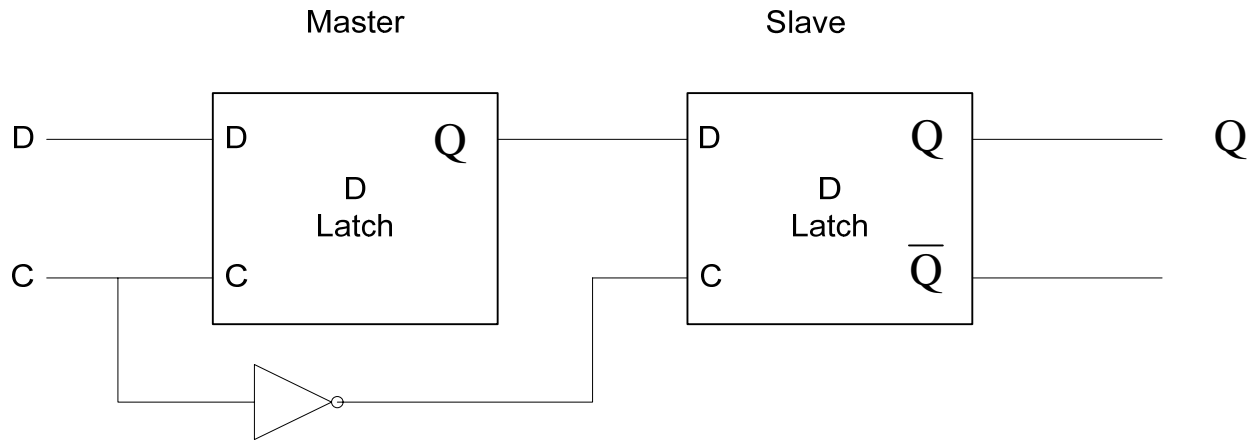
$$Q_{t+1} = J\bar{Q}_t + \bar{K}Q_t$$

Master Slave Flip Flop

Edge sensitive, Set up and Hold time

Master and Slave Flip Flop :

A D Flip Flop with a falling-edge trigger.



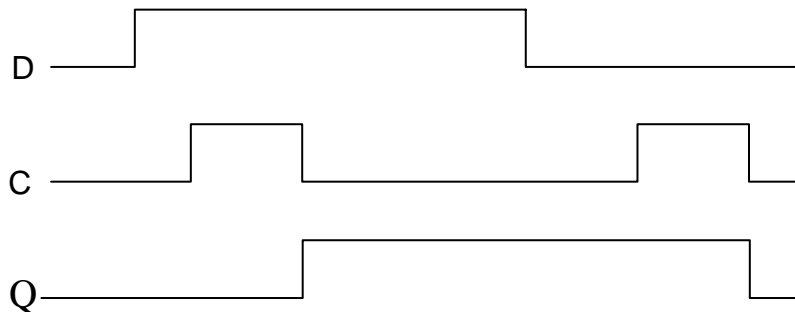
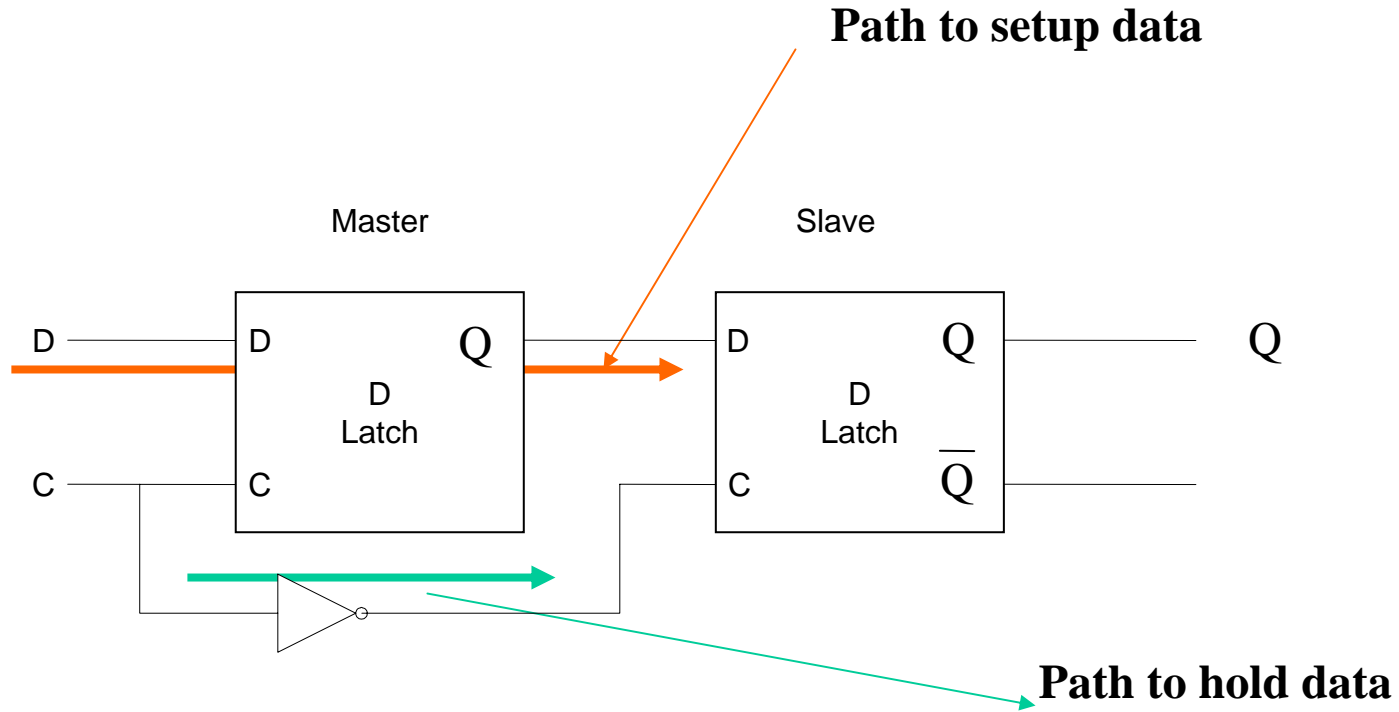
Master Slave Flip Flop Edge sensitive,-Falling Edge

Set Up and Hold Time constraints

Concordia

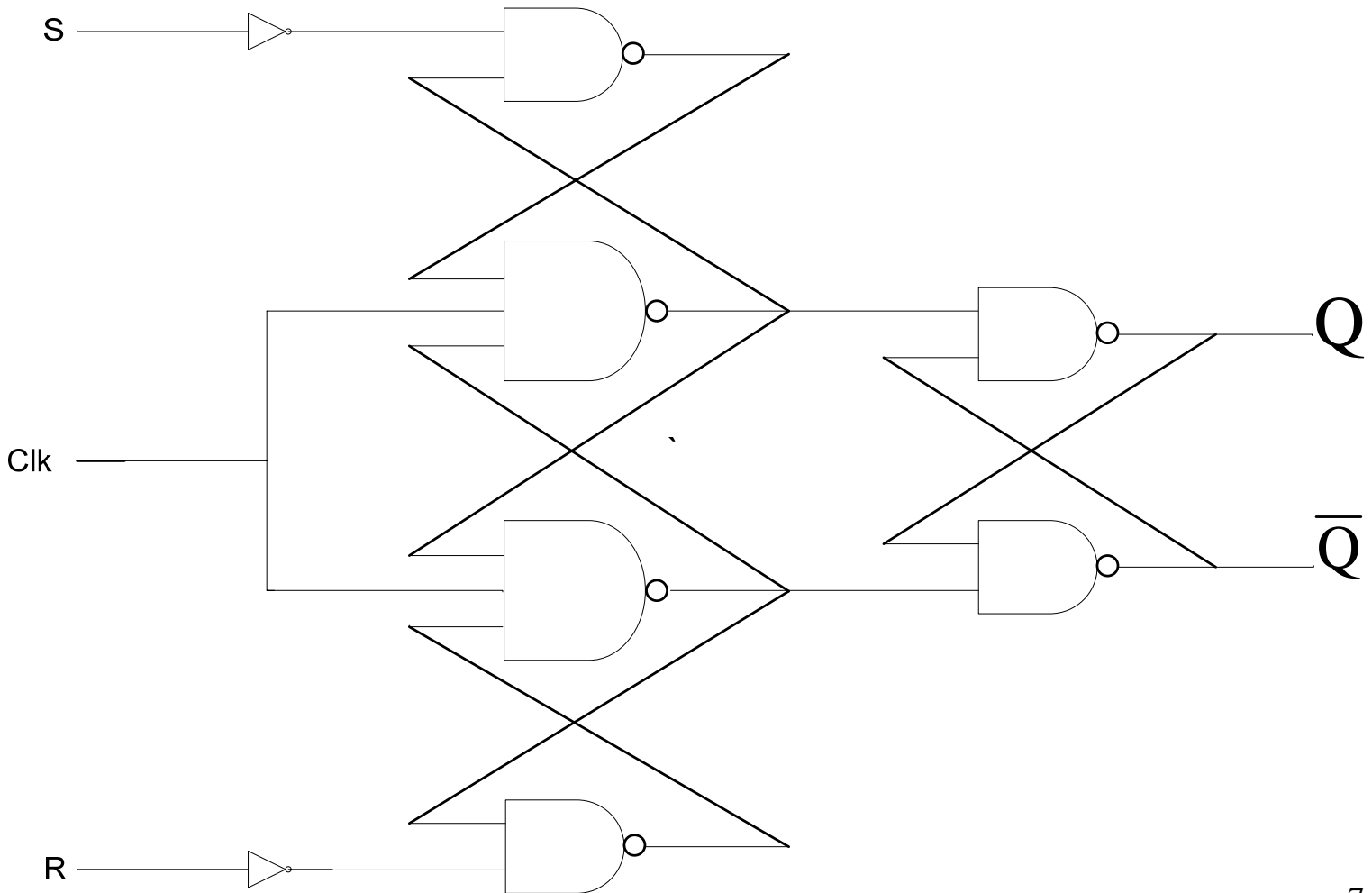


University



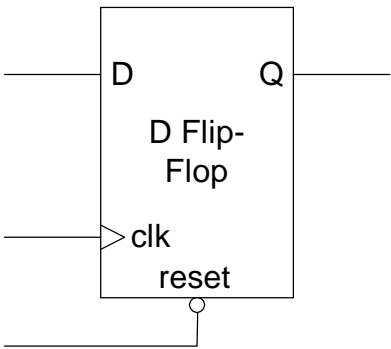
Edge triggered Flip Flop:

Set up and Hold time Constraints

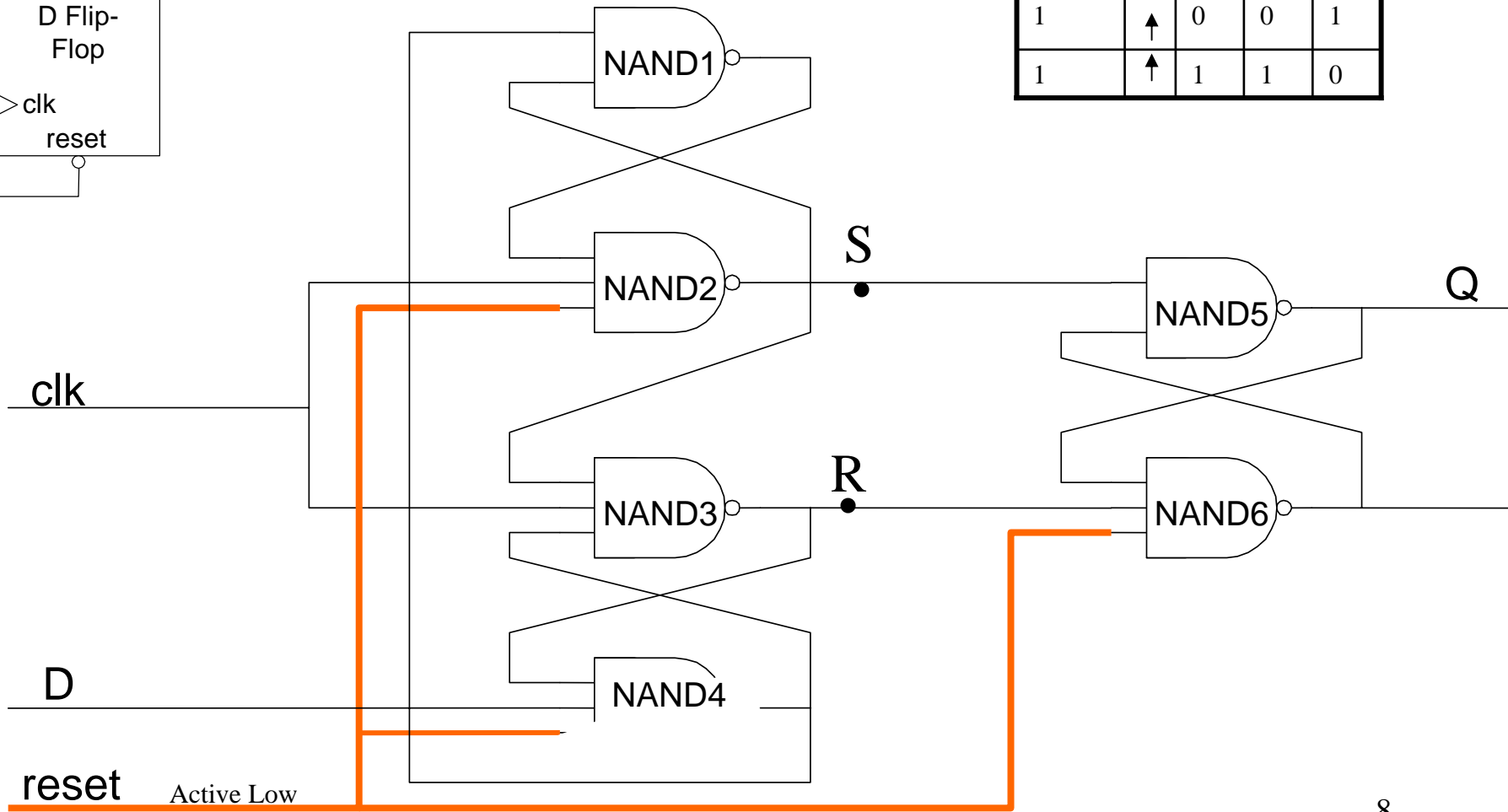


Edge Triggered, D Flip Flop,

With Reset

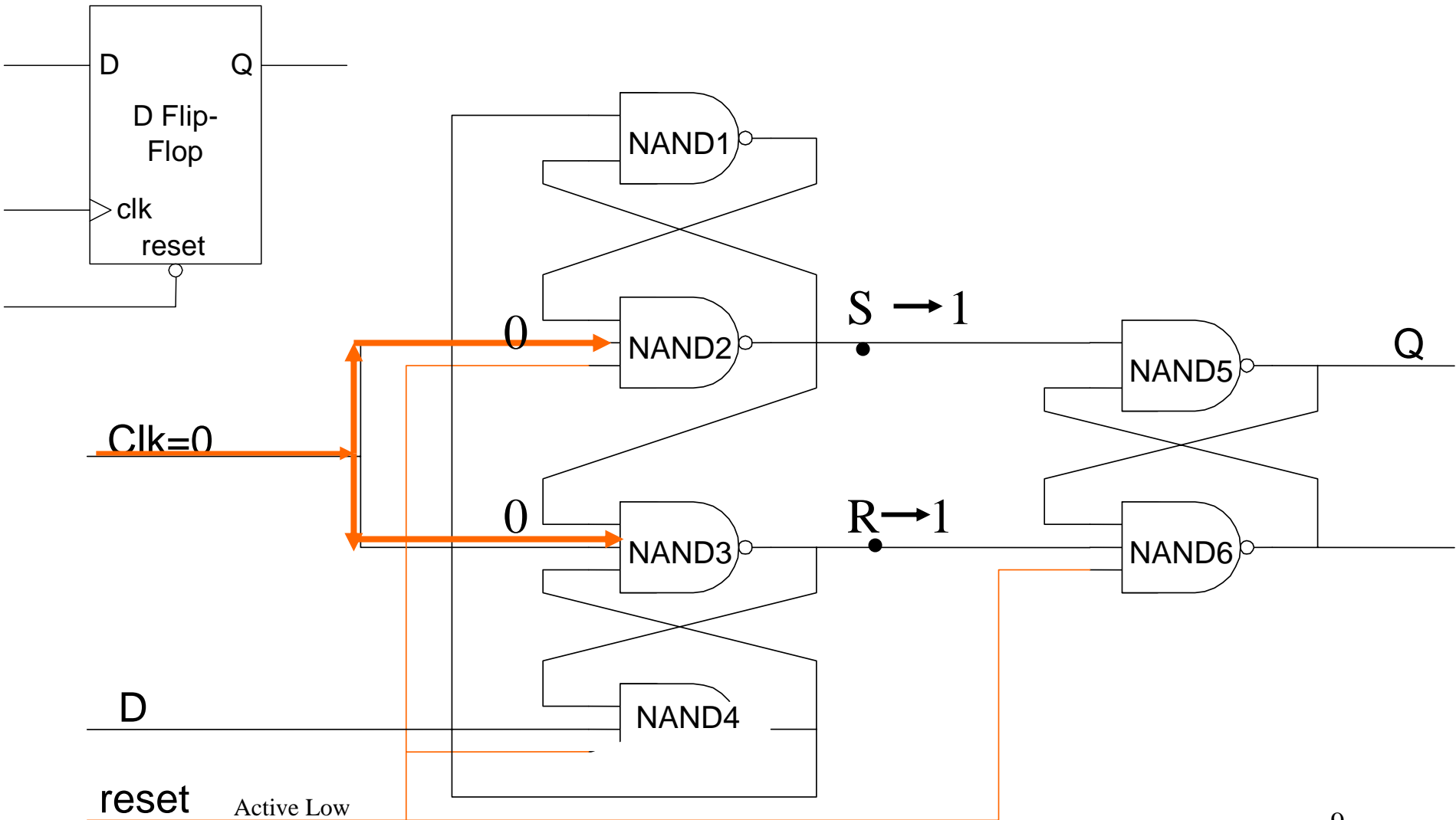


Reset	C	D	Q	Q'
0	X	X	0	1
1	↑	0	0	1
1	↑	1	1	0



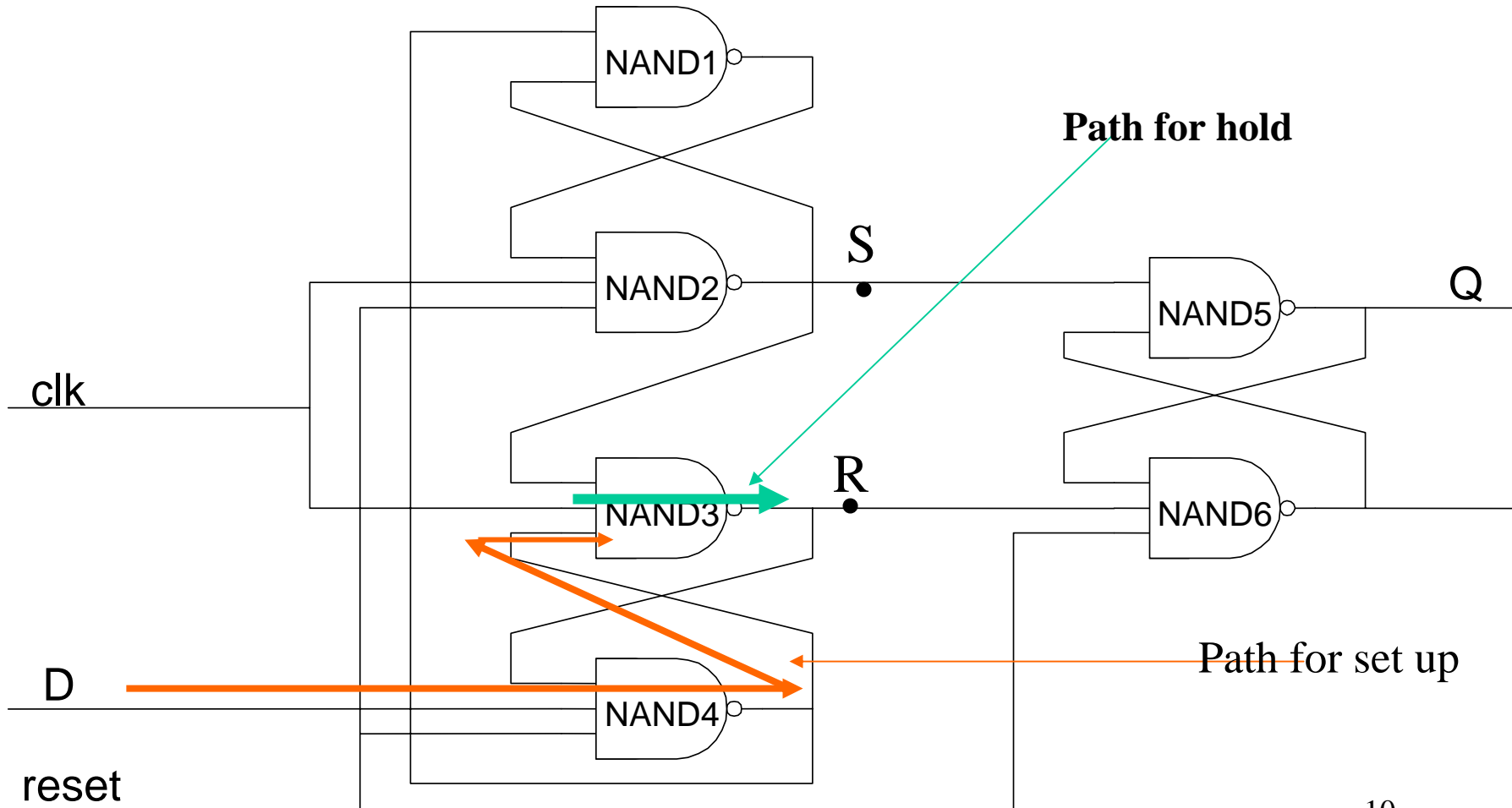
Edge Triggered, D Flip Flop

When CLK=0



When CLK changes from 0 to 1

Case1, D=0: $t_{\text{setup}} = t_4$, $t_{\text{hold}} = t_3$

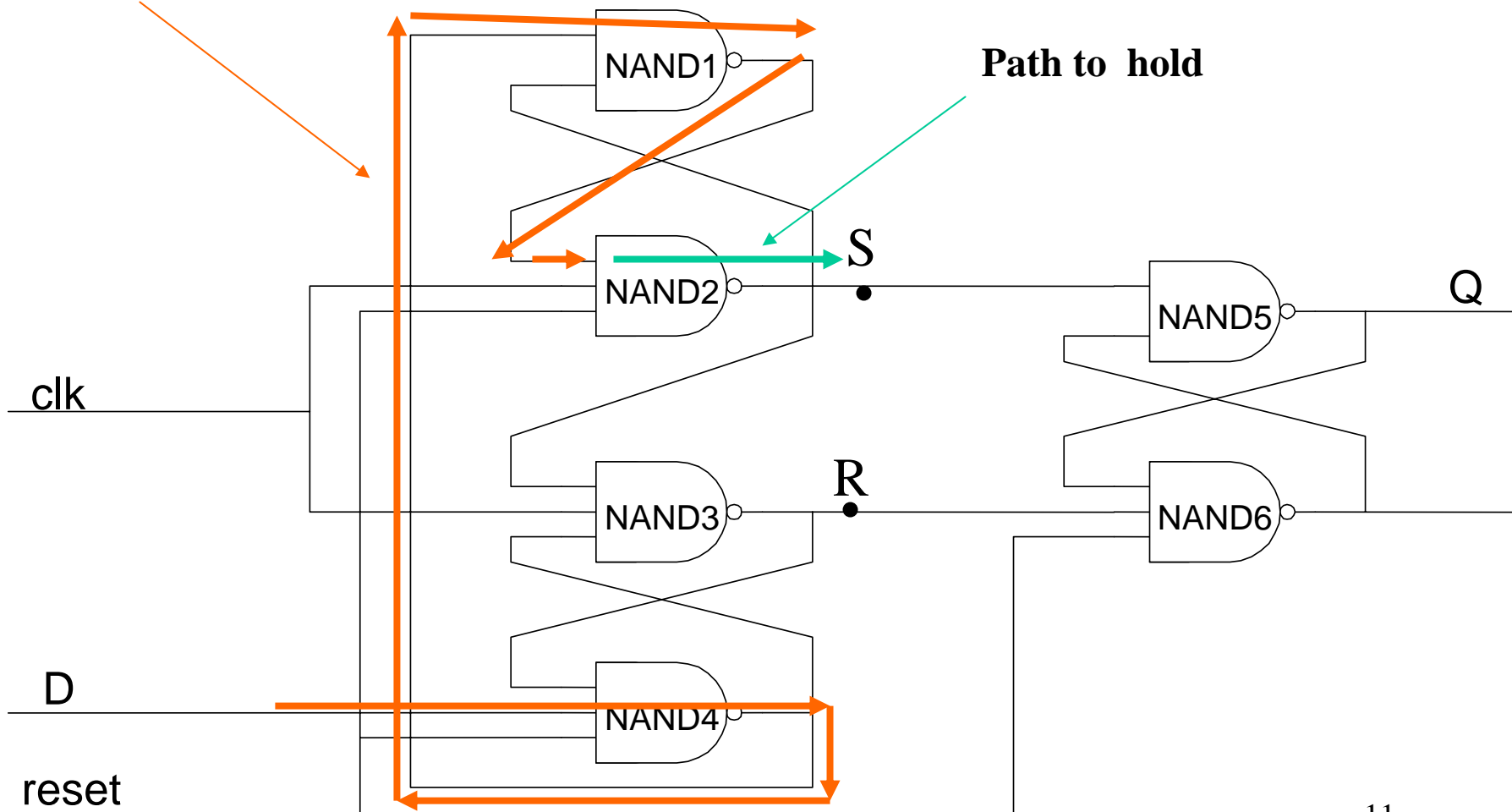


When CLK changes from 0 to 1

Case2, D=1 $t_{\text{setup}} = t_4 + t_1$ $t_{\text{hold}} = t_2$

Path to set up

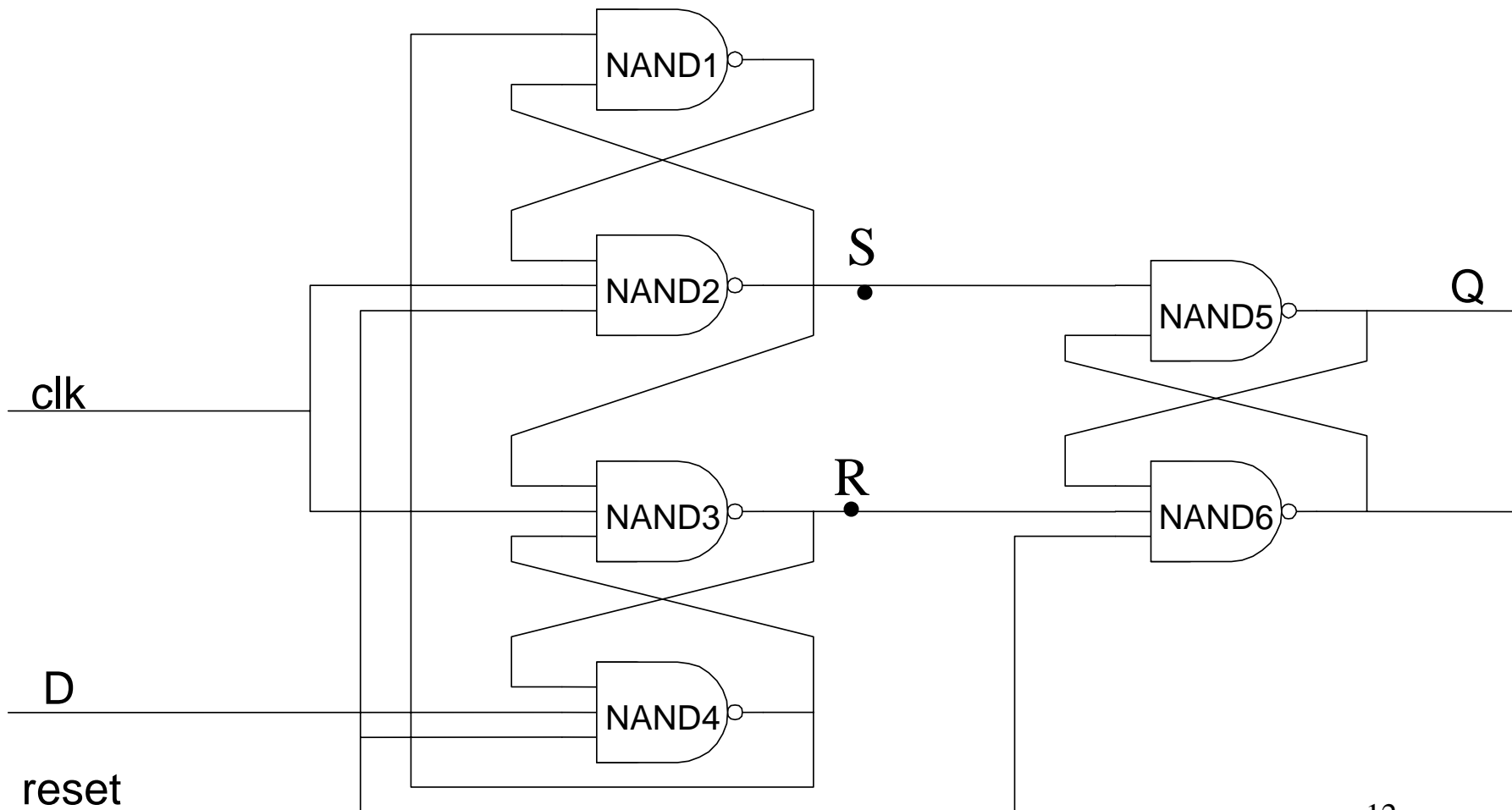
Path to hold



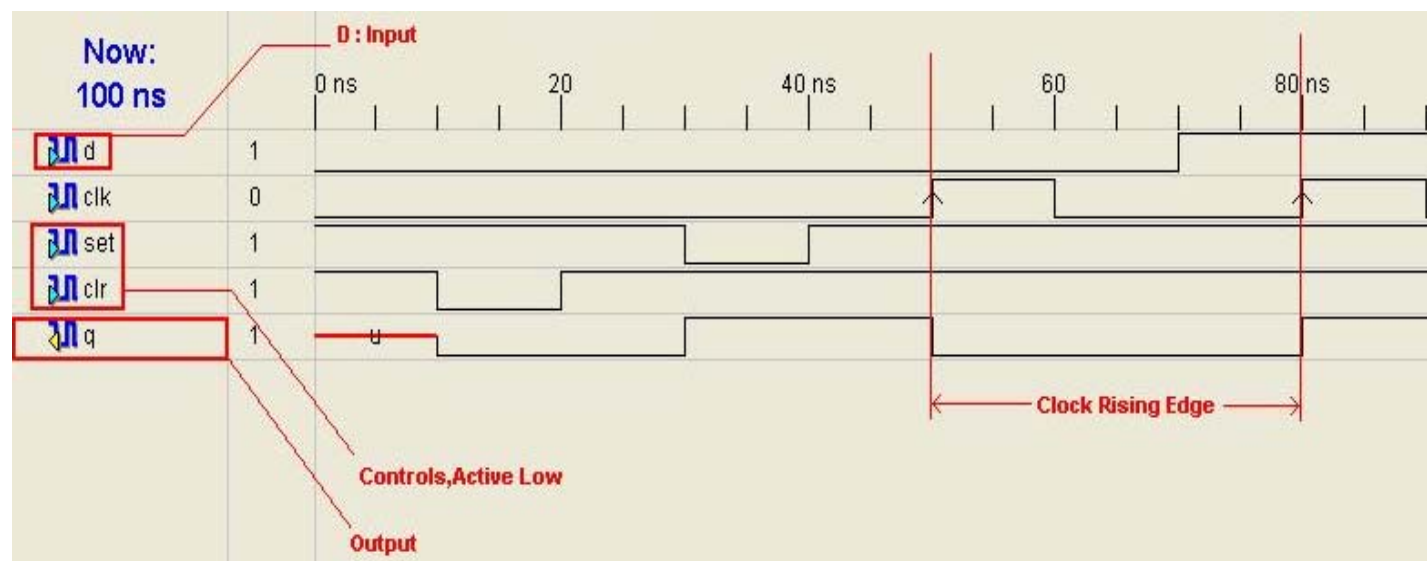
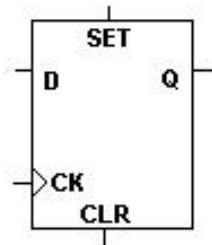
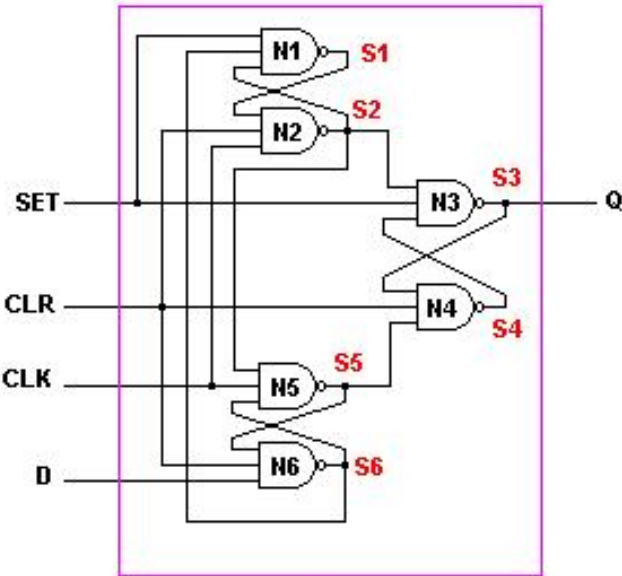
When CLK changes from 0 to 1

Case1, D=0: $t_{\text{setup}} = t_4$, $t_{\text{hold}} = t_3$

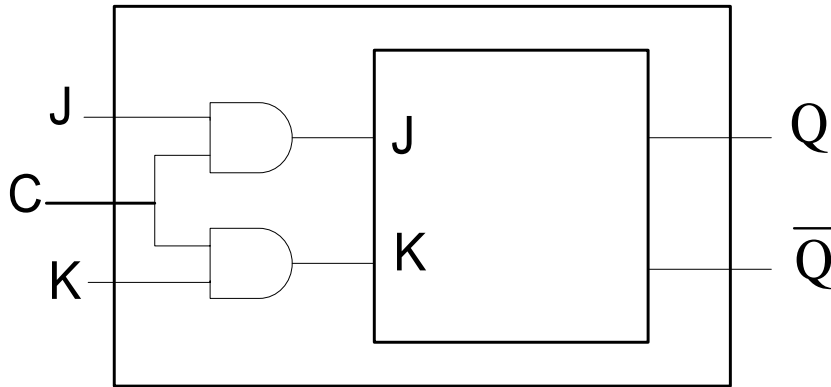
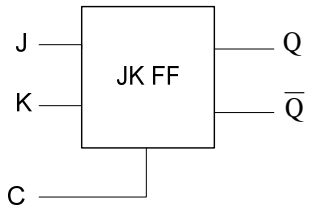
Case2, D=1 $t_{\text{setup}} = t_4 + t_1$ $t_{\text{hold}} = t_2$



D Flip Flop

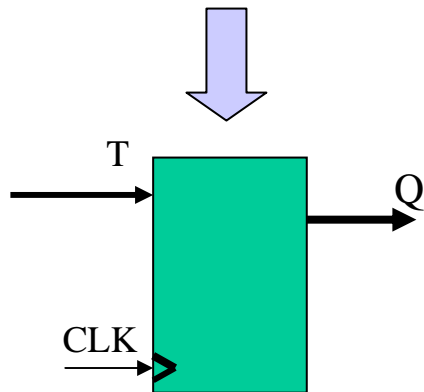
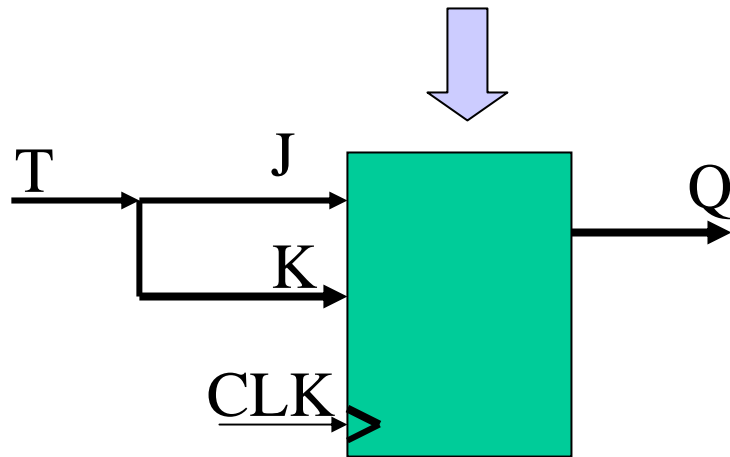
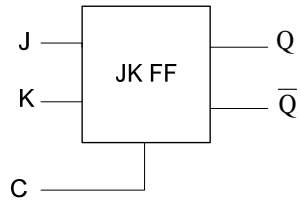


JK Flip Flop with a rising-edge :



$$Q^+ = JQ' + K'Q$$

T-Flip Flop



$$Q^+ = JQ' + K'Q$$

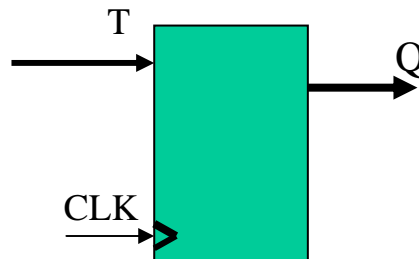
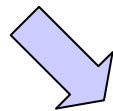
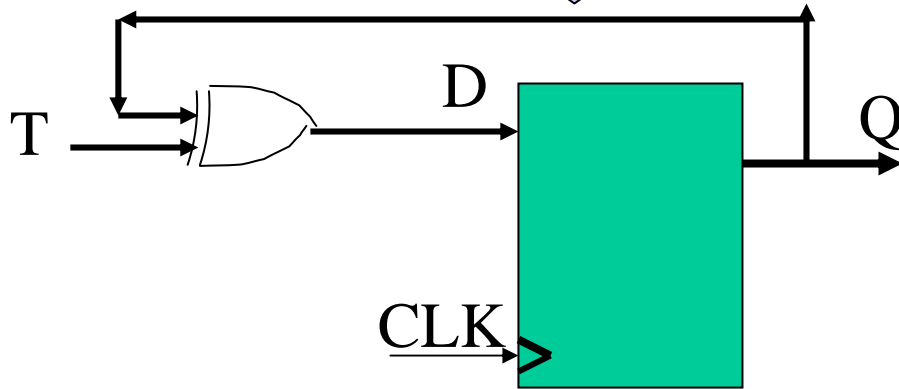
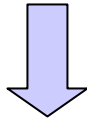
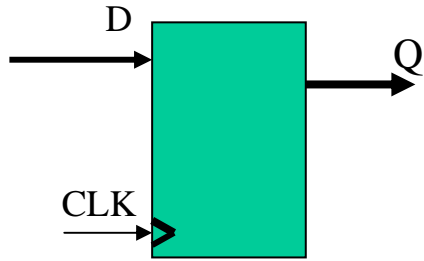
$$J=K=T$$

$$Q^+ = TQ' + T'Q$$

$$T=1 \quad Q^+ = Q'$$

$$T=0 \quad Q^+ = Q$$

T-Flip Flop



$$Q^+ = JQ' + K'Q$$

$$J=K=T$$

$$Q^+ = TQ' + T'Q$$

$$T=1 \quad Q^+ = Q'$$

$$T=0 \quad Q^+ = Q$$